				(	GANPAT	UNI	VERSITY							
		FA	CULT				NG & TEC	HNOLO	)GY					
Programme Master of Technology							Branch/Spec.	Electrica	gy)					
Semester			II				Version	1.0.0.0	5 <b>.</b> /					
Effective from Academic			Year		2025-2026		Effective for the	batch Adn	2025					
Course c			3EE11PE	.8	Course Name	<del>.</del>	Electrical Drive							
		Te	aching sch	eme			Exa							
			ure(DT)		ctical(Lab.)	Total	LA	tal						
		L	TU TU			Total		CE	SEE	<u> </u>				
Credit		3	0	1		4	Theory	40	60	10	00			
Hours 3			0	2		5	Practical	30	20	5				
Pre-requi	isites:						1							
-														
Course (	Outcomes:													
		letion	of the cou	rse, th	ne students wi	ll be able	e to:							
CO1					es and their a									
CO2	Demonstrate the drive controller.													
CO3	Understand Scalar control of electrical drives.													
CO4	Analysis of energy saving initiatives and EMI and EMC standards in brief.													
Theory s														
Unit	y ii dous					Conten	<u> </u>				Hrs			
Omt	Dynamica	of E	lootnio Dn	Troce.		Conten	•				1113			
1	Dynamics of Electric Drives:  Eundementals of torque equation Speed torque convention and multi-quadrent energian													
	Fundamentals of torque equation. Speed torque convention and multi-quadrant operation, Components of load torques.													
2	DC Motor Drives:  Modeling of DC machines, Steady state characteristics with armsture and speed control, Phase													
	Modeling of DC machines, Steady state characteristics with armature and speed control, Phase													
	controlled DC motor drives, Chopper controlled DC motor drives.  Poly-phase Induction Machines:													
						Small	signal equations	Control	characteristic	c of				
3							ne, Stator voltage				08			
							ction motor drive		ip energy reco	very				
				n and	vector control	or mau	ction motor drive.	o.						
4	Traction Motor:													
	Starting, Speed-Time characteristics, Braking, Traction motors used in practice.													
	Synchronous Machines:													
5	Steady-state equivalent circuits and dynamic model of synchronous machine; Zero d-axis current control, Maximum torque per ampere control, Direct torque control and power factor control.													
							orque control and	l power fact	tor control.					
	Electromagnetic Interference and Harmonics:													
6	Introduction to EMI and EMC, EMC for power converters, Grounding and shielding, EMC classes and Standards, Introduction to harmonics, Harmonic measurement techniques, Reduction methods													
-				on to	narmonics, H	armonic	measurement tec	enniques, R	eduction meti	noas				
Duactica	mitigation	toors	S.											
	l content	nte es	nd tutoriolo	are h	ased on above	cvlloby	o .							
Text Boo		ms al	ia tutoffals	are 0	ascu on above	symabu	o.							
1.		Par	o "Modow	2 Down	er Flastronica	and AC	Drives", Pearson	Education	Asia					
2.							alysis, and Contro			ia				
	ce Books	man,	Electric IV	OIOI I	Jiives. Model	mig, All	arysis, and Contro	n, r caisoil	Education mu	1a.				
1.		Dul	nev "Fund	ament	als of Flectric	al Drive	s", CRC Press, Se	econd Editio	nn .					
1.							Asynchronous Ma			ert Ac	ademic			
2.			ii, Ellergy V Germany.	201180	i vanon suate	5103 101 1	asylicinolious Wi	CIIIIC DIIV	cs, Lap Lamb	on Ac	adellile			
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2.	https://nptel.ac.in/content/storage2/courses/108104051/ui/Course_home-4.htm https://nptel.ac.in/courses/108/101/108101040/													
3.					3/107/1081010 3/107/1081070									
4.		_					051/chapter_5/5_i	ntro.html						
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Mapping of CO with PO and PSO:															
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	P09	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	3	1	2	1	2	1	0	2	3	1	1	2	3
CO2	2	0	3	0	2	1	1	1	0	2	2	2	0	0	0
CO3	2	0	2	0	3	0	1	1	1	1	1	1	2	3	1
CO4	1	1	2	1	3	0	0	0	1	1	0	2	2	3	2